Optimisation of generalisation re-calculation using partitioning

About myself

- Tomas Straupis, iTree
- Work as a GIS expert/project manager
- Hobby of creating maps
 - OpenStreetMap
 - National datasets

Generalisation

- Generalisation requires a lot of time (and resources)
- Higher quality generalisation requires even more time
- Data is updated more often therefore requiring constant re-generalisation



Time (t) needed to perform each generalisation operation could be expressed as:

$$t = t_o^* n_o$$

where:

- \mathbf{t}_{o} average time required to generalise one object
- n_o number of objects being generalised

Identify changes

- Identify changes
 - Of objects being generalised
 - Objects having an impact on generalisation
 - Important attributes
- Ways to identify the changes
 - Compare old/new datasets
 - Collect information on dataset changes

Generalisation impact

- Generalisation involves a number of neighbouring objects
- Changing one object can have an influence on how another object is generalised:
 - amalgamation
 - selection (removal)
 - typification (results much larger object)

Generalisation impact









Objects in cluster



Clusters

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Dirty clusters I

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Dirty clusters II

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Testing

• Calculating in parallel:

- Full generalisation
- Incremental generalisation
- Comparing results:
 - Find differences
 - (Find errors/inconsistencies)



Generalisation time



Other types of objects

- Works (should work) for:
 - buildings

- waterbodies (except waterways)
- Will not work for:
 - roads (might use ref numbers)
 - waterways/railways (might need splitting on straight'ish segments)
- Depends on the way one object impact another

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Further improvement

- Clusters could be split with natural boundaries (rivers, roads)
- Further refine re-calculation for specific scales





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